AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims

Claims 1-15 (Cancelled).

Claim 16 (Currently Amended) A gauge for use in a surgical procedure to determine a first angle in a first plane and a second angle in a second plane, said gauge comprising:

a body;

a plumb bob mounted to said body so as to hang under the influence of a local gravitational field, said plumb bob being rotatable relative to said body in both said first plane and said second plane so as to determine said first angle and said second angle respectively; and

a first connector disposed on said body of said gauge; and

a second connector including structure for attachment with a prosthetic component, said first connector and said second connector including corresponding structure for connection therebetween for mounting of said gauge ~~to a~~ between said prosthetic component and a predefined site of a patient to allow correlation between the predefined site of said patient and positioning of said prosthetic component.

Claim 17 (Previously Presented) The gauge according to claim 16, wherein a universal joint rotatably mounts said plumb bob to said body.

Claim 18 (Previously Presented) The gauge according to claim 17, wherein said universal joint is any one of: a ball joint; a singular pivot-point joint; an eye end joint; a tie rod end joint; or a rose joint.

Claim 19 (Previously Presented) The gauge according to claim 16, wherein said first plane is orthogonal to said second plane.

Claim 20 (Previously Presented) The gauge according to claim 16, wherein said plumb bob includes a pointer.

Claim 21 (Previously Presented) The gauge according to claim 20, wherein said body includes markings disposed adjacent said pointer.

Claim 22 (Previously Presented) The gauge according to claim 21, wherein a first sub-set of said markings corresponds to angular increments of said first angle and a second sub-set of said markings corresponds to angular increments of said second angle.

Claim 23-24 (Cancelled)

Claim 25 (Currently Amended) The gauge according to claim 16, wherein said surgical procedure is the insertion of an acetabular cup into a reamed acetabulum during hip replacement surgery, wherein the second connector is attached to the acetabular cup.

Claim 26 (Previously Presented) The gauge according to claim 25, wherein said first angle corresponds to an aversion of said acetabular cup relative to the reamed acetabulum.

Claim 27 (Previously Presented) The gauge according to claim 25, wherein said second angle corresponds to an abduction of said acetabular cup relative to the reamed acetabulum.

Claim 28 (Previously Presented) The gauge according to claim 16, wherein movement of the plumb bob relative to the body is damped.

Claim 29 (Currently Amended) A gauge for use in a surgical procedure to determine a first angle in a first plane and a second angle in a second plane, said gauge comprising:

a body;

a first plumb bob mounted to said body so as to hang under the influence of a local gravitational field, said first plumb bob being rotatable relative to said body in said first plane so as to determine said first angle;

a second plumb bob mounted to said body so as to hang under the influence of a local gravitational field, said second plumb bob being rotatable relative to said body in said second plane so as to determine said second angle; and

a first connector disposed on said body of saig gauage, and

a second connector including structure for attachment with a prosthetic component, said first connector and second connector including corresponding structure for connection therebetween for connection of said gauge ~~to a~~ between said prosthetic component and ~~of a~~ predefined site of a patient.

Claim 30 (Previously Presented) The gauge according to claim 29, wherein said first plumb bob is mounted to said body for rotation about a first axis and the second plumb bob is mounted to said body for rotation about a second axis, whereby said first axis is orthogonal to said second axis.